ETH Zurich
Department of Mechanical and Process Engineering Winter 06/07
Nonlinear Continuum Mechanics
Exercise 1

## 1 Useful Definitions or Concepts

### 1.1 Extracting components from vectors or tensors

By taking the dot product of the vector or tensor with the basis of interest, the components can be extracted.

$$
\begin{align*}
u_{i} & =\mathbf{u} \cdot \mathbf{e}_{i}  \tag{1}\\
A_{i j} & =\mathbf{e}_{i} \cdot \mathbf{A} \mathbf{e}_{j} \tag{2}
\end{align*}
$$

This allows the following representation in components.

$$
\begin{align*}
\mathbf{u} & =u_{i} \mathbf{e}_{i}  \tag{3}\\
\mathbf{A} & =A_{i j} \mathbf{e}_{i} \otimes \mathbf{e}_{j} \tag{4}
\end{align*}
$$

### 1.2 Tensor products

The tensor product of two vectors $\mathbf{a}, \mathbf{b}$ is defined as,

$$
\begin{equation*}
\mathbf{a} \otimes \mathbf{b} \tag{5}
\end{equation*}
$$

The dot product with vectors are defined by the following. It must be noted that taking the dot product in front of and behind the tensor are different.

$$
\begin{align*}
(\mathbf{a} \otimes \mathbf{b}) \mathbf{v} & =(\mathbf{b} \cdot \mathbf{v}) \mathbf{a}  \tag{6}\\
\mathbf{w} \cdot(\mathbf{a} \otimes \mathbf{b}) & =(\mathbf{w} \cdot \mathbf{a}) \mathbf{b} \tag{7}
\end{align*}
$$

In the Holzapfel book, Eqn. (7) is presented as,

$$
\begin{equation*}
\mathbf{w}(\mathbf{a} \otimes \mathbf{b})=(\mathbf{w} \cdot \mathbf{a}) \mathbf{b} \tag{8}
\end{equation*}
$$

without the $(\cdot)$. We present the version with the dot for consistency but one must remember that this $\mathbf{a} \otimes \mathbf{b}$ is not a vector but a tensor and that it is not interchangable with $\mathbf{v}$.

$$
\begin{equation*}
\mathbf{w} \cdot(\mathbf{a} \otimes \mathbf{b}) \neq(\mathbf{a} \otimes \mathbf{b}) \cdot \mathbf{w} \tag{9}
\end{equation*}
$$

### 1.3 Proving two thing are equal

In showing that two vectors $\mathbf{a}, \mathbf{b}$ are equal $(\mathbf{a}=\mathbf{b})$, this is equivalent to showing that the vector $\mathbf{a}-\mathbf{b}$ is equal to zero. This is equivalent to showing the following,

$$
\begin{equation*}
\forall \mathbf{v} \in \mathcal{V}, \quad(\mathbf{a}-\mathbf{b}) \cdot \mathbf{v}=\mathbf{0} \tag{10}
\end{equation*}
$$

In the same manner, to show that two tensors $\mathbf{A}, \mathbf{B}$ are equal,

$$
\begin{equation*}
\forall \mathbf{v}, \mathbf{w} \in \mathcal{V}, \quad \mathbf{w} \cdot(\mathbf{A}-\mathbf{B}) \mathbf{v}=\mathbf{0} \tag{11}
\end{equation*}
$$

### 1.4 The trace operator and transpose

The trace of the tensor product is defined as,

$$
\begin{equation*}
\operatorname{tr}(\mathbf{a} \otimes \mathbf{b})=\mathbf{a} \cdot \mathbf{b} \tag{12}
\end{equation*}
$$

and the transpose of a tensor is defined as,

$$
\begin{equation*}
\forall \mathbf{v}, \mathbf{w} \in \mathcal{V}, \quad \mathbf{w} \cdot \mathbf{A}^{T} \mathbf{v}=\mathbf{A} \mathbf{w} \cdot \mathbf{v} \tag{13}
\end{equation*}
$$

ETH Zurich
Department of Mechanical and Process Engineering Winter 06/07
Nonlinear Continuum Mechanics
Exercise 1
Prof. Dr. Sanjay Govindjee

## 2 Application of concepts or definitions

### 2.1 Show the component form of the dot product

## Problem:

Show that,

$$
\begin{equation*}
\mathbf{u} \cdot \mathbf{v}=u_{i} v_{i} \tag{14}
\end{equation*}
$$

## Solution:

Let $\mathbf{u}=u_{i} \mathbf{e}_{i}$ and $\mathbf{v}=v_{j} \mathbf{e}_{j}$. By inserting these in the relation above we obtain,

$$
\begin{align*}
\mathbf{u} \cdot \mathbf{v} & =\left(u_{i} \mathbf{e}_{i}\right) \cdot\left(v_{j} \mathbf{e}_{j}\right) \\
& =u_{i} v_{j}\left(\mathbf{e}_{i} \cdot \mathbf{e}_{j}\right) \\
& =u_{i} v_{j} \delta_{i j} \\
& =u_{i} v_{i} . \tag{15}
\end{align*}
$$

### 2.2 Further examples of tensor products

## Problem:

Prove the following relationship.

$$
\begin{equation*}
(\mathbf{a} \otimes \mathbf{b}) \cdot(\mathbf{c} \otimes \mathbf{d})=(\mathbf{b} \cdot \mathbf{c}) \mathbf{a} \otimes \mathbf{d} \tag{16}
\end{equation*}
$$

## Solution:

Let $\mathbf{v}$ be an arbitrary vector. Apply this to the tensor as follows.

$$
\begin{align*}
(\mathbf{a} \otimes \mathbf{b}) \cdot(\mathbf{c} \otimes \mathbf{d}) \mathbf{v} & =(\mathbf{a} \otimes \mathbf{b})(\mathbf{d} \cdot \mathbf{v}) \mathbf{c} \\
& =(\mathbf{d} \cdot \mathbf{v})(\mathbf{b} \cdot \mathbf{c}) \mathbf{a} \\
& =(\mathbf{b} \cdot \mathbf{c})(\mathbf{d} \cdot \mathbf{v}) \mathbf{a} \\
& =(\mathbf{b} \cdot \mathbf{c})(\mathbf{a} \otimes \mathbf{d}) \mathbf{v} \tag{17}
\end{align*}
$$

Since this relationship holds for any vector $\mathbf{v}$, the two tensors are equal.

## Problem:

Prove the relationship,

$$
\begin{equation*}
(\mathbf{a} \otimes \mathbf{b})^{T}=(\mathbf{b} \otimes \mathbf{a}) \tag{18}
\end{equation*}
$$

## Solution:

Let $\mathbf{v}$ and $\mathbf{w}$ be arbitrary vectors. Apply this to the tensor as follows.

$$
\begin{align*}
\mathbf{w} \cdot(\mathbf{a} \otimes \mathbf{b})^{T} \mathbf{v} & =(\mathbf{a} \otimes \mathbf{b}) \mathbf{w} \cdot \mathbf{v} \\
& =(\mathbf{b} \cdot \mathbf{w}) \mathbf{a} \cdot \mathbf{v} \\
& =\mathbf{w} \cdot(\mathbf{a} \cdot \mathbf{v}) \mathbf{b} \\
& =\mathbf{w} \cdot(\mathbf{b} \otimes \mathbf{a}) \mathbf{v} \tag{19}
\end{align*}
$$

Since this relationship holds for any vectors $\mathbf{v}, \mathbf{w}$, the two tensors are equal.

ETH Zurich
Department of Mechanical and Process Engineering Winter 06/07
Nonlinear Continuum Mechanics
Exercise 1
Prof. Dr. Sanjay Govindjee

## Problem:

Prove the following relationship.

$$
\begin{equation*}
\mathbf{A}(\mathbf{u} \otimes \mathbf{v})=(\mathbf{A} \mathbf{u}) \otimes \mathbf{v} \tag{20}
\end{equation*}
$$

## Solution:

Let $\mathbf{v}$ be an arbitrary vector. Apply this to the tensor as follows.

$$
\begin{align*}
\mathbf{A}(\mathbf{a} \otimes \mathbf{b}) \mathbf{v} & =\mathbf{A}(\mathbf{b} \cdot \mathbf{v}) \mathbf{a} \\
& =(\mathbf{b} \cdot \mathbf{v}) \mathbf{A} \mathbf{a} \\
& =(\mathbf{A} \mathbf{a} \otimes \mathbf{b}) \mathbf{v} \tag{21}
\end{align*}
$$

Since this relationship holds for any vector $\mathbf{v}$, the two tensors are equal.

ETH Zurich
Department of Mechanical and Process Engineering Winter 06/07
Nonlinear Continuum Mechanics
Exercise 1
Prof. Dr. Sanjay Govindjee

## 3 Exercises

## Problem:

Show that,

$$
\begin{equation*}
\mathbf{v}=\mathbf{A u} \tag{22}
\end{equation*}
$$

implies,

$$
\begin{equation*}
v_{i}=A_{i j} u_{j} \tag{23}
\end{equation*}
$$

## Solution:

Let $\mathbf{u}=u_{i} \mathbf{e}_{i}, \mathbf{v}=v_{j} \mathbf{e}_{j}$, and $\mathbf{A}=A_{i j} \mathbf{e}_{k} \otimes \mathbf{e}_{l}$. Inserting this into the above expresion gives,

$$
\begin{align*}
v_{j} \mathbf{e}_{j} & =A_{k l} \mathbf{e}_{k} \otimes \mathbf{e}_{l} u_{i} \mathbf{e}_{i} \\
& =A_{k l} u_{i}\left(\mathbf{e}_{k} \otimes \mathbf{e}_{l}\right) \mathbf{e}_{i} \\
& =A_{k l} u_{i} \delta_{l i} \mathbf{e}_{k} \\
& =A_{k i} u_{i} \mathbf{e}_{k} . \tag{24}
\end{align*}
$$

With this expression we take the inner product of both sides with basis vector $\mathbf{e}_{p}$,

$$
\begin{align*}
v_{j} \mathbf{e}_{j} \cdot \mathbf{e}_{p} & =A_{k i} u_{i} \mathbf{e}_{k} \cdot \mathbf{e}_{p} \\
v_{j} \delta_{j p} & =A_{k i} u_{i} \delta_{k p} \\
v_{p} & =A_{p i} u_{i} \tag{25}
\end{align*}
$$

Thus we have the desired result.
Alternatively we could show the relation by the following process. Starting with the first expression we take the inner product with the basis vector $\mathbf{e}_{p}$.

$$
\begin{align*}
\mathbf{e}_{p} \cdot \mathbf{v} & =\mathbf{e}_{p} \cdot \mathbf{A u} \\
& =\mathbf{e}_{p} \cdot \mathbf{A}\left(u_{i} \mathbf{e}_{i}\right) \\
& =u_{i} \mathbf{e}_{p} \cdot \mathbf{A} \mathbf{e}_{i} \\
v_{p} & =u_{i} A_{p i} \tag{26}
\end{align*}
$$

ETH Zurich
Department of Mechanical and Process Engineering Winter 06/07
Nonlinear Continuum Mechanics
Exercise 1
Prof. Dr. Sanjay Govindjee

## Problem:

Show that,

$$
\begin{equation*}
(\mathbf{a} \otimes \mathbf{b})_{i j}=a_{i} b_{j} . \tag{27}
\end{equation*}
$$

## Solution:

To obtain the component expression we select basis vectors $\mathbf{e}_{i}$ and $\mathbf{e}_{j}$ and apply them to the tensor as follows.

$$
\begin{align*}
\mathbf{e}_{i} \cdot(\mathbf{a} \otimes \mathbf{b}) \mathbf{e}_{j} & =\mathbf{e}_{i}\left(\mathbf{b} \cdot \mathbf{e}_{j}\right) \mathbf{a} \\
& =b_{j} \mathbf{e}_{i} \cdot \mathbf{a} \\
& =a_{i} b_{j} \tag{28}
\end{align*}
$$

Alternatively we can obtain the expression by the following.

$$
\begin{align*}
\mathbf{a} \otimes \mathbf{b} & =\left(a_{i} \mathbf{e}_{i}\right) \otimes\left(b_{j} \mathbf{e}_{j}\right) \\
& =a_{i} b_{j} \mathbf{e}_{i} \otimes \mathbf{e}_{j} \tag{29}
\end{align*}
$$

Since we know that,

$$
\begin{equation*}
\mathbf{a} \otimes \mathbf{b}=(\mathbf{a} \otimes \mathbf{b})_{i j} \mathbf{e}_{i} \otimes \mathbf{e}_{j} \tag{30}
\end{equation*}
$$

if we compare this with the expression above, we obtain the desired the result.

ETH Zurich
Department of Mechanical and Process Engineering Winter 06/07
Nonlinear Continuum Mechanics
Exercise 1
Center of Mechanics

Prof. Dr. Sanjay Govindjee

## Problem:

Prove the following relation.

$$
\begin{equation*}
(\mathbf{A B})^{T}=\mathbf{B}^{T} \mathbf{A}^{T} \tag{31}
\end{equation*}
$$

## Solution:

Let $\mathbf{v}$ and $\mathbf{w}$ be arbitrary vectors. Apply this to the tensor as follows.

$$
\begin{align*}
\mathbf{w} \cdot(\mathbf{A B})^{T} \mathbf{v} & =(\mathbf{A B}) \mathbf{w} \cdot \mathbf{v} \\
& =\mathbf{B w} \cdot \mathbf{A}^{T} \mathbf{v} \\
& =\mathbf{w} \cdot \mathbf{B}^{T} \mathbf{A}^{T} \mathbf{v} \tag{32}
\end{align*}
$$

Since this relationship holds for any vectors $\mathbf{v}, \mathbf{w}$, the two tensors are equal.
Alternatively we can work with the components to see that the expressions are equal. Let $\mathbf{A}=A_{i j} \mathbf{e}_{i} \otimes \mathbf{e}_{j}$ and $\mathbf{B}=B_{k l} \mathbf{e}_{k} \otimes \mathbf{e}_{l}$. Inserting this into the expression we have,

$$
\begin{aligned}
(\mathbf{A B})^{T} & =\left(A_{i j} \mathbf{e}_{i} \otimes \mathbf{e}_{j} \cdot B_{k l} \mathbf{e}_{k} \otimes \mathbf{e}_{l}\right)^{T} \\
& =\left(A_{i j} B_{k l} \mathbf{e}_{i} \otimes \mathbf{e}_{j} \cdot \mathbf{e}_{k} \otimes \mathbf{e}_{l}\right)^{T}
\end{aligned}
$$

By using Eqn. (16).

$$
\begin{align*}
(\mathbf{A B})^{T} & =A_{i j} B_{k l}\left(\mathbf{e}_{i} \otimes \mathbf{e}_{l} \delta_{j k}\right)^{T} \\
& =A_{i j} B_{k l} \delta_{j k}\left(\mathbf{e}_{i} \otimes \mathbf{e}_{l}\right)^{T} \tag{33}
\end{align*}
$$

Using the relation shown in Eqn. (18), we have,

$$
\begin{equation*}
(\mathbf{A B})^{T}=A_{i j} B_{j l}\left(\mathbf{e}_{l} \otimes \mathbf{e}_{i}\right) \tag{34}
\end{equation*}
$$

Next we evaluate the right hand side of the problem.

$$
\begin{align*}
\mathbf{B}^{T} \mathbf{A}^{T} & =\left(B_{k l} \mathbf{e}_{k} \otimes \mathbf{e}_{l}\right)^{T}\left(A_{i j} \mathbf{e}_{i} \otimes \mathbf{e}_{j}\right)^{T} \\
& =B_{k l} A_{i j}\left(\mathbf{e}_{k} \otimes \mathbf{e}_{l}\right)^{T}\left(\mathbf{e}_{i} \otimes \mathbf{e}_{j}\right)^{T} \\
& =B_{k l} A_{i j}\left(\mathbf{e}_{l} \otimes \mathbf{e}_{k}\right)\left(\mathbf{e}_{j} \otimes \mathbf{e}_{i}\right) \tag{35}
\end{align*}
$$

Here we have again used Eqn. (18). Next we use Eqn. (16).

$$
\begin{align*}
\mathbf{B}^{T} \mathbf{A}^{T} & =B_{k l} A_{i j} \delta_{k j} \mathbf{e}_{l} \otimes \mathbf{e}_{i} \\
& =B_{j l} A_{i j} \mathbf{e}_{l} \otimes \mathbf{e}_{i} \tag{36}
\end{align*}
$$

Comparing Eqn. (33) and Eqn. (36) we obtain the desired result.

Department of Mechanical and Process Engineering Winter 06/07
Nonlinear Continuum Mechanics
Exercise 1

## Problem:

Show the relationship,

$$
\begin{align*}
\mathbf{A}: \mathbf{B} & =\operatorname{tr}\left(\mathbf{A}^{T} \mathbf{B}\right) \\
& =A_{i j} B_{i j} \tag{37}
\end{align*}
$$

## Solution:

$$
\begin{align*}
\mathbf{A}: \mathbf{B} & =\operatorname{tr}\left(\mathbf{A}^{T} \mathbf{B}\right) \\
& =\operatorname{tr}\left(\left(A_{i j} \mathbf{e}_{i} \otimes \mathbf{e}_{j}\right)^{T} \cdot B_{k l} \mathbf{e}_{k} \otimes \mathbf{e}_{k}\right) \\
& =A_{i j} B_{k l} \operatorname{tr}\left(\mathbf{e}_{j} \otimes \mathbf{e}_{i} \cdot \mathbf{e}_{k} \otimes \mathbf{e}_{l}\right) \\
& =A_{i j} B_{k l} \operatorname{tr}\left(\delta_{i k} \mathbf{e}_{j} \otimes \mathbf{e}_{l}\right) \\
& =A_{i j} B_{k l} \delta_{i k} \mathbf{e}_{j} \cdot \mathbf{e}_{l} \\
& =A_{i j} B_{i l} \delta_{j l} \\
& =A_{i j} B_{i j} \tag{38}
\end{align*}
$$

## 4 Homework

### 4.1 Show that the following relationships hold

$$
\begin{align*}
\operatorname{tr}(\mathbf{A}) & =\mathbf{1}: \mathbf{A}  \tag{39}\\
\mathbf{A}: \mathbf{B C} & =\left(\mathbf{B}^{T} \mathbf{A}\right): \mathbf{C}=\left(\mathbf{A} \mathbf{C}^{T}\right): \mathbf{B}  \tag{40}\\
\mathbf{A}:(\mathbf{u} \otimes \mathbf{v}) & =\mathbf{u} \cdot \mathbf{A} \mathbf{v}=(\mathbf{u} \otimes \mathbf{v}): \mathbf{A} \tag{41}
\end{align*}
$$

Hint: Express the vectors and tensors in component form, i.e. $\mathbf{a}=a_{i} \mathbf{e}_{i}$ and $\mathbf{A}=A_{i j} \mathbf{e}_{i} \otimes \mathbf{e}_{j}$ and insert in the relations above. Use the definition of the double contraction ":".

### 4.2 Projections operators

Given a direction $\mathbf{e}$, an arbitrary vector a can be decomposed into the component parallel to $\mathbf{e}$ which we denote $\mathbf{a}_{\|}$and the component in the plane normal to $\mathbf{e}$ we denote as $\mathbf{a}_{\perp}$. They are defined as,

$$
\begin{align*}
\mathbf{a} & =\mathbf{a}_{\|}+\mathbf{a}_{\perp}  \tag{42}\\
\mathbf{a}_{\|} & =(\mathbf{a} \cdot \mathbf{e}) \mathbf{e}  \tag{43}\\
\mathbf{a}_{\perp} & =\mathbf{a}-\mathbf{a}_{\|} \tag{44}
\end{align*}
$$

Corresponding to these we define projection tensors,

$$
\begin{align*}
\mathbf{P}_{e}^{\|} & =\mathbf{e} \otimes \mathbf{e}  \tag{45}\\
\mathbf{P}_{e}^{\perp} & =\mathbf{1}-\mathbf{P}_{e}^{\|} \tag{46}
\end{align*}
$$

4.2.1 Verify that $\mathbf{P}_{e}^{\|} \mathbf{a}=\mathbf{a}_{\|}, \mathbf{P}_{e}^{\perp} \mathbf{a}=\mathbf{a}_{\perp}$, and $\mathbf{a}_{\|} \cdot \mathbf{a}_{\perp}=0$

### 4.2.2 Verify the following expressions.

$$
\begin{align*}
\mathbf{P}_{e}^{\|} \mathbf{P}_{e}^{\|} & =\mathbf{P}_{e}^{\|}  \tag{47}\\
\mathbf{P}_{e}^{\perp} \mathbf{P}_{e}^{\perp} & =\mathbf{P}_{e}^{\perp}  \tag{48}\\
\mathbf{P}_{e}^{\perp} \mathbf{P}_{e}^{\|} & =\mathbf{0} \tag{49}
\end{align*}
$$

### 4.3 Decomposition into symmetric and skew parts

Every tensor A can be decomposed into its symmetric and skew parts. They are defined as follows.

$$
\begin{align*}
\mathbf{A} & =\frac{1}{2}\left(\mathbf{A}+\mathbf{A}^{T}\right)+\frac{1}{2}\left(\mathbf{A}-\mathbf{A}^{T}\right) \\
& =\mathbf{A}_{\text {symm }}+\mathbf{A}_{\text {skew }} \tag{50}
\end{align*}
$$

where,

$$
\begin{align*}
\mathbf{A}_{\text {symm }} & =\frac{1}{2}\left(\mathbf{A}+\mathbf{A}^{T}\right)  \tag{51}\\
\mathbf{A}_{\text {skew }} & =\frac{1}{2}\left(\mathbf{A}-\mathbf{A}^{T}\right) \tag{52}
\end{align*}
$$

ETH Zurich
Department of Mechanical and Process Engineering Winter 06/07
Nonlinear Continuum Mechanics
Exercise 1
Prof. Dr. Sanjay Govindjee
skew parts. Recall that a symmetric tensor $\mathbf{S}$ has the property,

$$
\begin{equation*}
\mathbf{S}^{T}=\mathbf{S} \tag{53}
\end{equation*}
$$

and a skew tensor $\mathbf{W}$ has the property,

$$
\begin{equation*}
\mathbf{W}^{T}=-\mathbf{W} \tag{54}
\end{equation*}
$$

4.3.1 Show that, $A_{\text {symm }}$ is indeed symmetric and that $A_{\text {skew }}$ is indeed skew. In other words show,

$$
\begin{align*}
\mathbf{A}_{\text {symm }}^{T} & =\mathbf{A}_{\text {symm }}  \tag{55}\\
\mathbf{A}_{\text {skew }}^{T} & =-\mathbf{A}_{\text {skew }} \tag{56}
\end{align*}
$$

4.3.2 Then show that for a symmetric tensor $S$ and skew symmetric tensor $W$,

$$
\begin{equation*}
\mathbf{S}: \mathbf{W}=0 \tag{57}
\end{equation*}
$$

Hint: Write out the expression in components and think about what structure the components of $\mathbf{S}$ and $\mathbf{W}$ have.

