

Phonon dispersion computations

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Equations of Motion

$$m_k \ddot{q}_{\alpha(k)}^{(A)} = - \sum_{\beta, B, n} K_{\alpha(k)\beta(n)}^{(A)B} q_{\beta(n)}^{(B)}$$

- To solve we make a plane-wave plus a periodic (Born – v. Karmen) assumption:

$$q_{\alpha(k)}^{(A)}(t) = \hat{q}_{\alpha k}(\omega, \mathbf{f}) e^{i(\mathbf{x}_A \cdot \mathbf{f} - \omega t)}$$

$$q_{\alpha(k)}^{(N+1)} = q_{\alpha(k)}^{(1)}$$

- Assuming N lattice cells in each coordinate direction.
- $\mathbf{x}_A = \mathbf{F} \mathbf{X}_A$, if deformation.

Implications of Periodicity

- Consider a fixed lattice direction $x_A = Aa_1$. The periodic BC implies

$$e^{i(N+1)\mathbf{a}_1 \cdot \mathbf{f}} = e^{i\mathbf{a}_1 \cdot \mathbf{f}}$$

- Define the (dual) reciprocal vectors \mathbf{b}_j via $\mathbf{b}_j \cdot \mathbf{a}_i = \delta_{ij}$; i.e. $\mathbf{b}_i = (\mathbf{a}_j \times \mathbf{a}_k) / [\mathbf{a}_1, \mathbf{a}_2, \mathbf{a}_3]$, where i, j, k are a cyclic permutation of $\{1, 2, 3\}$. If one expands \mathbf{f} as $\mathbf{f} = f_1\mathbf{b}_1 + f_2\mathbf{b}_2 + f_3\mathbf{b}_3$, then

$$f_1 = \frac{2\pi n_1}{N} \quad n_1 \in \mathbb{J}$$

- In general $\mathbf{f} \in \left(\frac{2\pi n_1}{N}, \frac{2\pi n_2}{N}, \frac{2\pi n_3}{N}\right)$ where $n_1, n_2, n_3 \in \mathbb{J}$.

Restricted Wave Vector Range

- The unique (physically) distinct solutions only occur for

$$n_i \in \{0, 1, \dots, N - 1\}$$

- Or any shifted set of integers of “length” N .
- This follows since adding N to a wave vector index, say $2\pi n/N \rightarrow 2\pi(n + N)/N$, yields

$$e^{i2\pi(n+N)/N} = e^{i2\pi n} e^{i2\pi} = e^{i2\pi n}$$

Eigen Equations

- Using our expansion in the equations of motion

$$-m_k \omega^2(\mathbf{f}) \hat{q}_{\alpha k}(\omega, \mathbf{f}) e^{i\mathbf{x}_A \cdot \mathbf{f}} = - \sum_{\beta, B, n} K_{\alpha \binom{A}{k} \beta \binom{B}{n}} \hat{q}_{\beta n} e^{i\mathbf{x}_B \cdot \mathbf{f}}$$

- The sum over B ranges over all cells in the crystal but effectively is restricted to just those that interact with the atom at $\binom{A}{k}$.
- Without loss of generality, let us focus on the cell $A = 1$ and assume $\mathbf{x}_A = \mathbf{0}$. Define the dynamical matrix

$$D_{\alpha k \beta n} = \sum_B K_{\alpha \binom{1}{k} \beta \binom{B}{n}} e^{i\mathbf{x}_B \cdot \mathbf{f}}$$

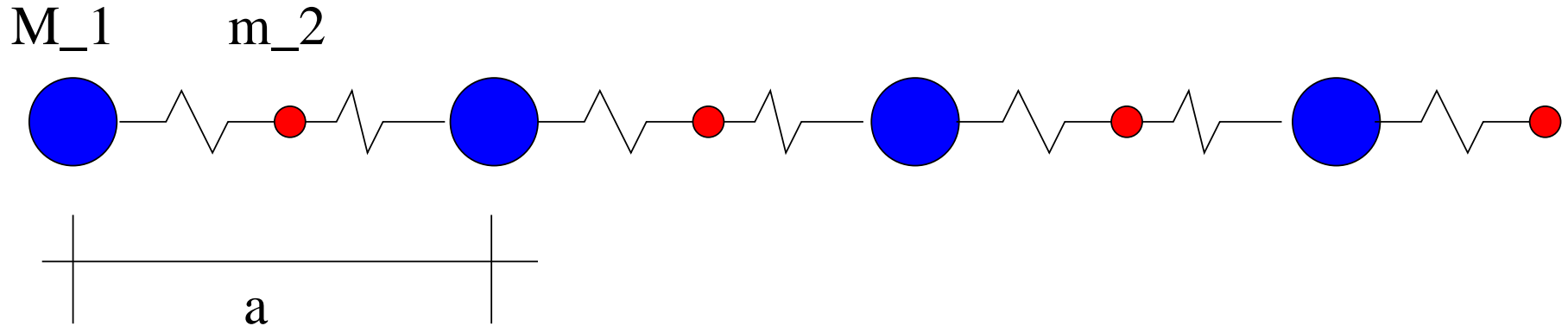
Phonon Spectra Equation

- We are now left with the eigenproblem

$$\left| D_{(\alpha k)(\beta n)}(\mathbf{f}) - m_k \omega^2(\mathbf{f}) I_{(\alpha k)(\beta n)} \right| = 0$$

- This is a $3s \times 3s$ eigenvalue problem that needs to be solved for each acceptable \mathbf{f} of which there are $N^3 = N_c$.
- By symmetry considerations one can greatly reduce the number of needed computations.
- All the binding energy of the crystal is hidden inside the dynamical matrix which contains the crystal stiffness.
- The result is valid for full finite deformation states as long as the stiffness is computed with respect to the deformed (Cauchy-Born) lattice positions (with basis relaxation).

1D example with 2 atom basis



- 2 atom basis $s = 2$
- 1 dof per atom
- N lattice cells

Equations in 1D

- In 1D we can drop the α, β subscripts to give:

$$m_k \ddot{q}_{(k)}^{(A)} = - \sum_{B,n} K_{(k)(n)}^{(A)(B)} q_{(n)}^{(B)}$$

- The corresponding Ansatz is:

$$q_{(k)}^{(A)}(t) = \hat{q}_k(\omega, f) e^{i(x_A f - \omega t)}$$

where $x_A = (A - 1)a$ and by the Born – v. Karmen conditions $f = 2\pi n/aN$.

Dynamical Matrix

- The dynamical matrix in this setting will be

$$D_{kn}(f) = \sum_B e^{ix_B f} K_{(k)(n)}^{(1)(B)}$$

- To compute let us assume that $\phi(l_b) = \frac{1}{2}C(l_b - l_o)^2$ and that interactions only occur with respect to neighboring atoms (nearest neighbor approximation).

Stiffness and Dynamical Matrix

- Potential Energy (skip self interaction terms)

$$V = \frac{1}{2} \sum_{A,B,k,n} \phi(|r_{(k)}^{(A)} - r_{(n)}^{(B)}|)$$

Stiffness and Dynamical Matrix

● Forces

$$\begin{aligned}\frac{\partial V}{\partial r_{(m)}^{(C)}} &= \frac{1}{2} \sum_{A,B,k,n} \phi'(|r_{(k)}^{(A)} - r_{(n)}^{(B)}|) \frac{r_{(k)}^{(A)} - r_{(n)}^{(B)}}{|r_{(k)}^{(A)} - r_{(n)}^{(B)}|} \\ &\quad [\delta_{AC}\delta_{km} - \delta_{BC}\delta_{mn}] \\ &= \sum_{B,n} \phi'(|r_{(m)}^{(C)} - r_{(n)}^{(B)}|) \frac{r_{(m)}^{(C)} - r_{(n)}^{(B)}}{|r_{(m)}^{(C)} - r_{(n)}^{(B)}|}\end{aligned}$$

Stiffness and Dynamical Matrix

• The stiffness

$$\begin{aligned} \frac{\partial^2 V}{\partial r_{(m)}^{(C)} \partial r_{(p)}^{(D)}} &= \sum_{B,n} \phi''(|r_{(m)}^{(C)} - r_{(n)}^{(B)}|) \frac{r_{(m)}^{(C)} - r_{(n)}^{(B)}}{|r_{(m)}^{(C)} - r_{(n)}^{(B)}|} \\ &\quad \frac{r_{(m)}^{(C)} - r_{(n)}^{(B)}}{|r_{(m)}^{(C)} - r_{(n)}^{(B)}|} [\delta_{CD} \delta_{mp} - \delta_{BD} \delta_{np}] \\ &+ \phi'(|r_{(m)}^{(C)} - r_{(n)}^{(B)}|) \frac{\partial}{\partial r_{(p)}^{(D)}} \frac{r_{(m)}^{(C)} - r_{(n)}^{(B)}}{|r_{(m)}^{(C)} - r_{(n)}^{(B)}|} \\ &= \sum_{B,n} \phi''(|r_{(m)}^{(C)} - r_{(n)}^{(B)}|) [\delta_{CD} \delta_{mp} - \delta_{BD} \delta_{np}] \end{aligned}$$

Stiffness and Dynamical Matrix

- The Dynamical matrix

$$\begin{aligned} D_{mp} &= \sum_D e^{ix_D f} \left\{ \sum_{B,n} \phi''(|x_{(m)}^{(1)} - x_{(n)}^{(B)}|) [\delta_{1D} \delta_{mp} - \delta_{BD} \delta_{np}] \right\} \\ &= \sum_{B,n} \phi''(|x_{(m)}^{(1)} - x_{(n)}^{(B)}|) \delta_{mp} e^{i \cdot 0} \\ &\quad - \sum_D e^{ix_D f} \phi''(|x_{(m)}^{(1)} - x_{(p)}^{(D)}|) \end{aligned}$$

Stiffness and Dynamical Matrix

- The Dynamical matrix

$$D_{mp} = \begin{bmatrix} 2C & 0 \\ 0 & 2C \end{bmatrix} \\ - \begin{bmatrix} 0 & C \\ 0 & 0 \end{bmatrix} e^{-iaf} \\ - \begin{bmatrix} 0 & C \\ C & 0 \end{bmatrix} e^{i \cdot 0} \\ - \begin{bmatrix} 0 & 0 \\ C & 0 \end{bmatrix} e^{iaf}$$

Stiffness and Dynamical Matrix

- The Dynamical matrix

$$D_{mp} = C \begin{bmatrix} 2 & -(1 + e^{-iaf}) \\ -(1 + e^{iaf}) & 2 \end{bmatrix}$$

Final eigencomputation

- Eigenvalue problem

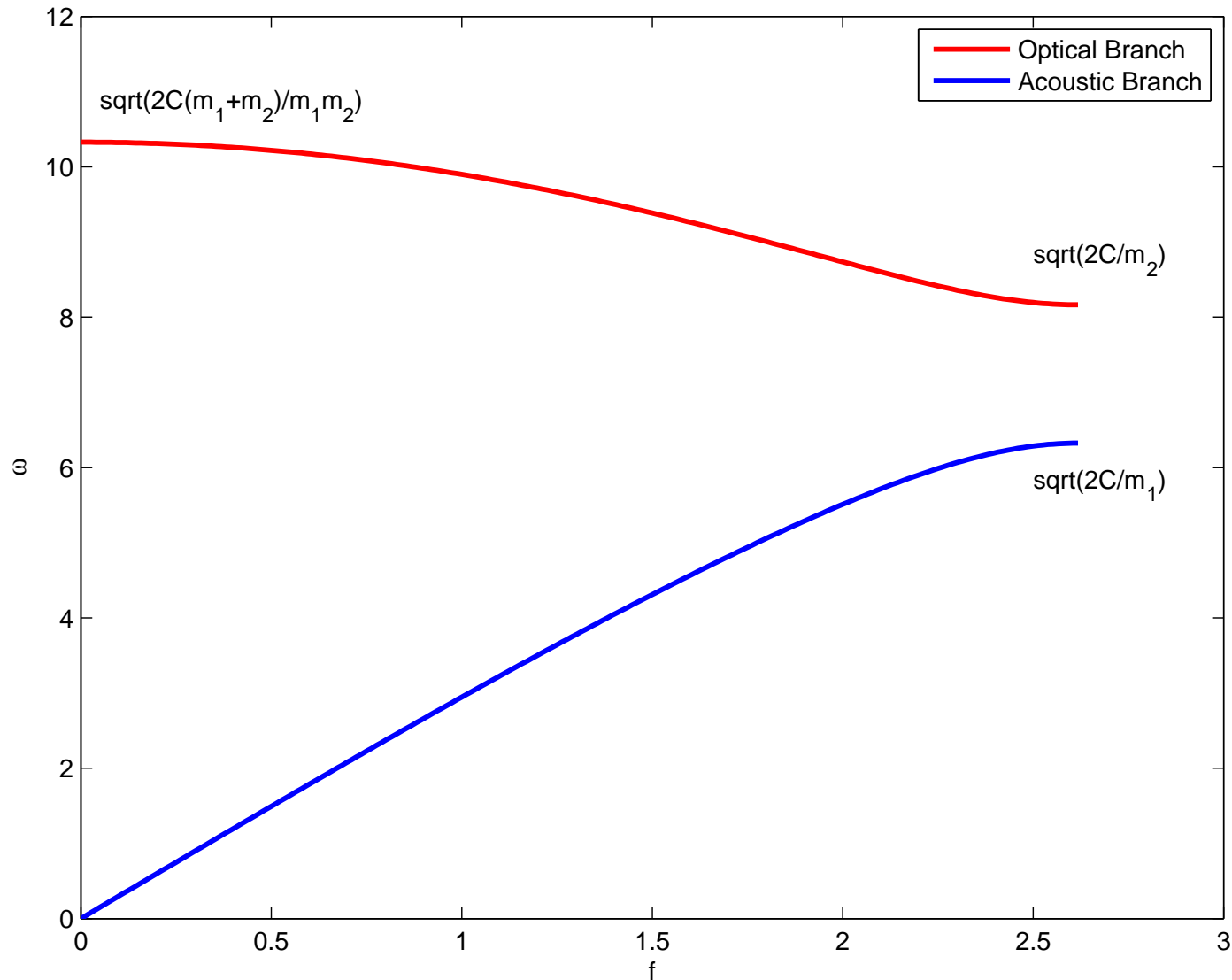
$$\left| C \begin{bmatrix} 2 & -(1 + e^{-iaf}) \\ -(1 + e^{iaf}) & 2 \end{bmatrix} - \omega^2(f) \begin{bmatrix} m_1 & 0 \\ 0 & m_2 \end{bmatrix} \right| = 0$$

- Solutions

$$\omega^2(f) = \frac{C(m_1 + m_2)}{m_1 m_2} \left[1 \pm \sqrt{1 - \frac{2m_1 m_2 (1 - \cos(fa))}{(m_1 + m_2)^2}} \right]$$

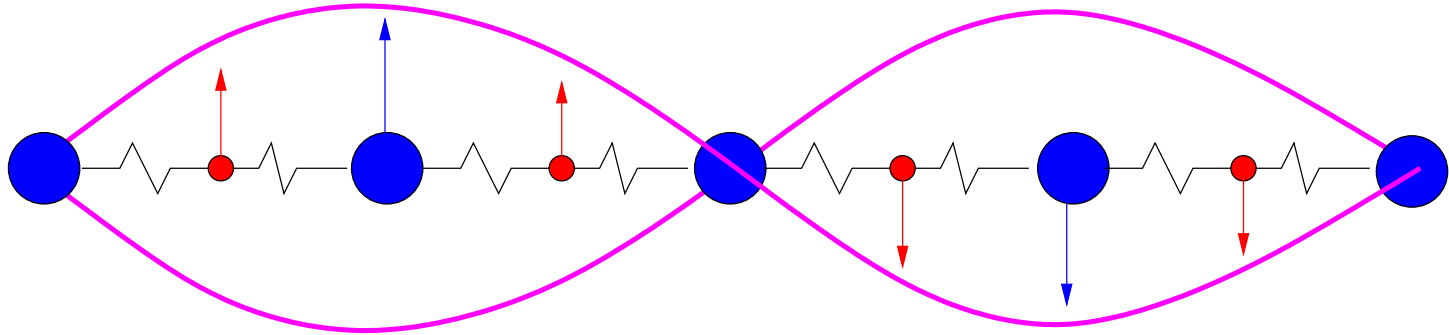
Dispersion Curves

$a = 1.2, m_1 = 50, m_2 = 30, C = 1000$

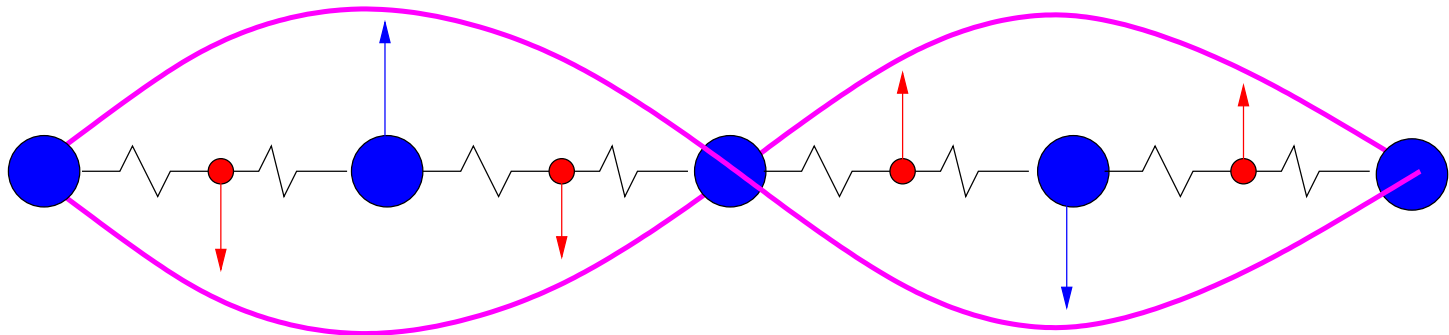


Branches

- Acoustic branch eigenvector $f = \frac{\pi}{2a} \rightarrow \lambda = \frac{2\pi}{f} = 4a$



- Optical branch eigenvector $f = \frac{\pi}{2a} \rightarrow \lambda = \frac{2\pi}{f} = 4a$



Remarks

- Per space dimension, d , one has 1 acoustic branch ([P,SV,SH] in 3D).
- $(s - 1) \cdot d$ optical branches.
- $s \cdot d$ branches in total
- Continuous curves are shown but they are really discrete.
- Slopes correspond to the group velocities $d\omega/df$ which govern the velocity of energy transport.

Multi-D Case

- The potential depends on $V(\mathbf{F} \mathbf{X}_A + \mathbf{b}_k + \mathbf{q}_{(k)}^{(A)})$ where the \mathbf{b}_k need to be found by minimizing the crystal energy for the given deformation state.
- Assuming such, as well as pair potentials, and noting

$$\mathbf{r}_{(k)}^{(A)} = \underbrace{\mathbf{F} \mathbf{X}_A + \mathbf{b}_k}_{\mathbf{x}_{(k)}^{(A)}} + \mathbf{q}_{(k)}^{(A)}, \text{ gives}$$

$$V = \frac{1}{2} \sum_{A,B,k,n} \phi(\|\mathbf{r}_{(k)}^{(A)} - \mathbf{r}_{(n)}^{(B)}\|)$$

Forces

$$\begin{aligned}\frac{\partial V}{\partial \mathbf{r}_{(m)}^{(C)}} &= \frac{1}{2} \sum_{A,B,k,n} \phi'(\|\mathbf{r}_{(k)}^{(A)} - \mathbf{r}_{(n)}^{(B)}\|) \frac{\mathbf{r}_{(k)}^{(A)} - \mathbf{r}_{(n)}^{(B)}}{\|\mathbf{r}_{(k)}^{(A)} - \mathbf{r}_{(n)}^{(B)}\|} \\ &\quad [\delta_{AC}\delta_{km} - \delta_{BC}\delta_{mn}] \\ &= \sum_{B,n} \phi'(\|\mathbf{r}_{(m)}^{(C)} - \mathbf{r}_{(n)}^{(B)}\|) \frac{\mathbf{r}_{(m)}^{(C)} - \mathbf{r}_{(n)}^{(B)}}{\|\mathbf{r}_{(m)}^{(C)} - \mathbf{r}_{(n)}^{(B)}\|}\end{aligned}$$

Stiffness

$$\begin{aligned}
 \frac{\partial^2 V}{\partial \mathbf{r}_{(m)}^{(C)} \partial \mathbf{r}_{(p)}^{(D)}} &= \sum_{B,n} \left\{ \phi''(\|\mathbf{r}_{(m)}^{(C)} - \mathbf{r}_{(n)}^{(B)}\|) \frac{\mathbf{r}_{(m)}^{(C)} - \mathbf{r}_{(n)}^{(B)}}{\|\mathbf{r}_{(m)}^{(C)} - \mathbf{r}_{(n)}^{(B)}\|} \right. \\
 &\quad \otimes \frac{\mathbf{r}_{(m)}^{(C)} - \mathbf{r}_{(n)}^{(B)}}{\|\mathbf{r}_{(m)}^{(C)} - \mathbf{r}_{(n)}^{(B)}\|} [\delta_{CD}\delta_{mp} - \delta_{BD}\delta_{np}] \\
 &\quad + \phi'(\|\mathbf{r}_{(m)}^{(C)} - \mathbf{r}_{(n)}^{(B)}\|) \left[\frac{\mathbf{1}\delta_{DC}\delta_{mp} - \mathbf{1}\delta_{DB}\delta_{pn}}{\|\mathbf{r}_{(m)}^{(C)} - \mathbf{r}_{(n)}^{(B)}\|} \right. \\
 &\quad - \frac{(\mathbf{r}_{(m)}^{(C)} - \mathbf{r}_{(n)}^{(B)}) \otimes (\mathbf{r}_{(m)}^{(C)} - \mathbf{r}_{(n)}^{(B)})}{\|\mathbf{r}_{(m)}^{(C)} - \mathbf{r}_{(n)}^{(B)}\|^3} \\
 &\quad \left. \left. [\delta_{DC}\delta_{mp} - \delta_{BD}\delta_{pn}] \right] \right\}
 \end{aligned}$$

Dynamical Matrix (3×3 block)

$$\begin{aligned}
 \mathbf{D}_{mp}(\mathbf{f}) &= \sum_D e^{i\mathbf{x}_D \cdot \mathbf{f}} \mathbf{K}_{(m)(p)}^{(1)(D)} \\
 &= \delta_{mp} \sum_{B,n} \left\{ \phi''(\|\boldsymbol{\beta}\|) \frac{\boldsymbol{\beta} \otimes \boldsymbol{\beta}}{\|\boldsymbol{\beta}\|^2} + \phi'(\|\boldsymbol{\beta}\|) \left[\frac{\mathbf{1}}{\|\boldsymbol{\beta}\|} - \frac{\boldsymbol{\beta} \otimes \boldsymbol{\beta}}{\|\boldsymbol{\beta}\|^3} \right] \right\} \\
 &\quad + \sum_D \left\{ e^{i\mathbf{x}_D \cdot \mathbf{f}} \left[\phi'(\|\mathbf{v}\|) \left(\frac{\mathbf{v} \otimes \mathbf{v}}{\|\mathbf{v}\|^3} - \frac{\mathbf{1}}{\|\mathbf{v}\|} \right) - \phi''(\|\mathbf{v}\|) \frac{\mathbf{v} \otimes \mathbf{v}}{\|\mathbf{v}\|^2} \right] \right\}
 \end{aligned}$$

$$\boldsymbol{\beta} = \mathbf{x}_{(1)}^{(m)} - \mathbf{x}_{(n)}^{(B)} \quad \text{and} \quad \mathbf{v} = \mathbf{x}_{(1)}^{(m)} - \mathbf{x}_{(p)}^{(D)}$$

Final Matrices

- Dynamical Matrix

$$D = \begin{bmatrix} D_{11} & D_{12} & \cdots & D_{1s} \\ D_{21} & \ddots & & \vdots \\ \vdots & & \ddots & \vdots \\ D_{s1} & \cdots & \cdots & D_{ss} \end{bmatrix}$$

- Mass Matrix

$$I = \begin{bmatrix} m_1 \mathbf{1} & & & \\ & m_2 \mathbf{1} & & \\ & & \ddots & \\ & & & m_s \mathbf{1} \end{bmatrix}$$

Remarks

- Self energy terms are to be skipped, i.e. when $v = 0$ and $\beta = 0$.
- Reasonable units for such computations are Å and eV. This implies force = eV/Å $\approx 1.6 \times 10^{-9}$ N.
- If mass is given in a.m.u. (grams per mole) then computed frequencies are in units of roughly 0.49 THz.