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WCCM8/ECCOMAS 2008 Congress: 20 June - 4 July 2008

Outline: Presentation summarizes:

- Historical overview
 - Early FEM developments by R.W. Clough
 - Berkeley-Swansea connection.
- Some of the work of people who have influenced FEM and me!
 - Near incompressibility treatment
 - Time integration algorithms
 - Computational mechanics at UC
 - Finite deformation
- Some challenges I see today.

Early History





Berkeley Campus 1940



UC Engineering Buildings ~1960

Karl Pister's 1962-63 Graduates!



1962

1995

• FEM: The engineeering begining

- Clough spent summers of 1952-53 and 1953-54 at Boeing.
- Worked with M.J. Turner, L.J. Topp and H.C. Martin (U. Wash).
- Credits Turner with idea of *elements* to determine frequencies of Delta wing aircraft.
- Names FEM in 1960
- My first class in 1957!



R.W. Clough (1956)

1956: First Berkeley and Engineering FEM paper.



Stiffness and Deflection Analysis of Complex Structures

M. J. TURNER,* R. W. CLOUGH,† H. C. MARTIN,‡ AND L. J. TOPP**

- FEM: The begining
 - Direct physical construction: Plane stress elasticity



• Linear displacements: Constant Strain Nodal forces by equilibrium.

• FEM: Results from first paper



- Earlier contribution from mathematics.
- 1941 presentation to American Math Society.
- Reference: "Variational methods for the solution of problems of equilibrium and vibration", Bulletin of the American Math Society, **49**, 1943, pp. 1–61.
- Solved Laplace equation problem (torsion).
- Not known to engineers in mid-1950's.



R. Courant (1941)

FEM Software Development:

- In addition to theoretical studies, FEM programs written.
- 1956: First campus machine IBM 701 in Cory Hall.
- Early program in assembly code (before FORmula TRANslator developed by Backus, *et al.* at IBM – 1954-57).
- Ed Wilson (Clough's student) prepared first UC program in FOR-TRAN II (1958) using IBM 704.
- Wilson's programs formed basis of all our early efforts.
- All early programs used 3-node triangle as basic element.

Early Computing Environment



Keypunch room

IBM Key Punch

• See Wilson's web page for more on early FEM research by Clough: http://www.edwilson.org

EARLY FINITE ELEMENT RESEARCH AT BERKELEY¹

by

Ray W. Clough Nishkian Professor of Structural Engineering, Emeritus University of California, Berkeley

and

Edward L. Wilson T. Y. Lin Professor of Structural Engineering, Emeritus University of California, Berkeley

Nearly Incompressible Analyses

- 1960-68: Solid propellant rocket analyses
- Propellant materials had properties making nearly incompressible ($\nu \approx 0.5$) and time dependent
- Displacement method gave poor results for $\nu > 0.4$.
- Improved using mixed methods displacement/pressure
- Based on paper by: Herrmann & Toms: J. Appl. Mech, 1964
- Used 4-triangle quadrilateral with constant pressure.
- Developed 2-d programs for elastic and thermoviscoelastic materials.



• Constitutive form: (L.R. Herrmann)

$$\sigma_{ij} = 2\mu \left[\epsilon_{ij} + (\nu H - e_T) \,\delta_{ij} \right]$$
$$H = \frac{3\sigma_{kk}}{2\mu(1+\nu)}$$
$$\epsilon_{kk} - e_T = (1-2\nu)H$$

- Elements (composite)
- Interpolations: u_i linear, H constant. (Before BB papers!)

INTERNATIONAL JOURNAL FOR NUMERICAL METHODS IN ENGINEERING, VOL. 2, 45-59 (1970)

THERMOMECHANICAL ANALYSIS OF VISCOELASTIC SOLIDS

ROBERT L. TAYLOR Associate Professor of Civil Engineering

KARL S. PISTER Professor of Engineering Science

and

GERALD L. GOUDREAU Graduate Student in Civil Engineering University of California, Berkeley



Thermoviscoelasticity:

• Constitution: Spherical/Deviatoric split

$$\sigma_{ij} = p \,\delta_{ij} + s_{ij} \quad ; \quad \epsilon_{kl} = \theta \,\delta_{kl} + e_{kl}$$

$$p = 3 \,K \left(\theta - \alpha \Delta T\right) \quad ; \quad s_{ij} = 2 \,G \!\int_{-\infty}^{t} \!G(\xi(t) - \xi(\tau), T_0) \frac{\partial e_{ij}}{\partial \tau} \,\mathrm{d}\tau$$

• Thermorheologically simple

$$\xi(t) = \int_0^t \phi(T(t')) \,\mathrm{d}t'$$

• Relaxation function: Prony series representation

$$G(\xi) = G\left[\mu_0 + \sum_{m=1}^{M} \mu_m \exp(\xi/\lambda_m)\right] \quad ; \quad \mu_0 + \sum_{m=1}^{M} \mu_m = 1$$

• Integration of Prony series form of constitution

$$\mathbf{s} = 2G \left[\mu_0 \mathbf{e} + \sum_{m=1}^M \mu_m \mathbf{q}^m \right]$$

• Recursion for increment t_n to t_{n+1}

$$\mathbf{q}^{m} = \int_{-\infty}^{t} \exp\left[-\left(\xi(t) - \xi(\tau)\right)/\lambda_{m}\right] \frac{\partial \mathbf{e}}{\partial \tau} \,\mathrm{d}\tau$$
$$\approx \exp\left[-\delta\xi_{n+1}/\lambda_{m}\right] \left[\mathbf{e}_{n+1} - \mathbf{e}_{n}\right] + \Delta q_{n+1}^{m} \left[\mathbf{e}_{n+1} - \mathbf{e}_{n}\right]$$
where $\left[\Delta\xi_{n+1} = \xi(t_{n+1}) - \xi(t_{n}) \approx \frac{1}{2} \left(\phi(T_{n}) + \phi(T_{n+1})\right) \Delta t\right]$:

$$\Delta q_{n+1}^m = \frac{\lambda_m}{\Delta \xi_{n+1}} \left[1 - \exp(-\Delta \xi_{n+1}/\lambda_m) \right]$$
$$= 1 - \frac{1}{2} \left(\frac{\Delta \xi_{n+1}}{\lambda_m} \right) + \frac{1}{3!} \left(\frac{\Delta \xi_{n+1}}{\lambda_m} \right)^2 - \frac{1}{4!} \left(\frac{\Delta \xi_{n+1}}{\lambda_m} \right)^3 + \cdots$$

Example: Thin-walled cylinder

• Normalized temperature

$$\bar{\theta}(x,\rho) = (1-x)[1-\exp(-2\rho)]$$

where ρ is normalized time, is x normalized thickness distance

• Properties

 $K = 2.5 \times 10^{10}$ $G = 8.3 \times 10^{9}$ $\mu_0 = 0.001$ $\mu_1 = 0.999$



Figure 3. Hoop stress versus time, temperature-dependent properties; \bigcirc , per THVISC, Reference 16; —, per Reference 7

• Shift function for polymethylmethacrylate

 $\phi(\bar{\theta}) = 3981.1 \exp[-6.2172(1-\bar{\theta})(1.3333 + \bar{\theta} + 1.095\,\bar{\theta}^2]$

Connections to Swansea

- 1965-70: FEM Major Advancements
 - Isoparametric elements (I. Taig 1962: Work done 1957-58).
 - Numerical integration (Irons 1966).
 - Thin/thick plates & shells (Zienkiewicz, et al. 1965ff)
- Swansea clearly an active FEM research location!
- 1968: Introduced to Zienkiewicz by Clough on airplane to 2nd Wright-Patterson conference.
- 1969: Sabbatical leave in Swansea (returned in 1976 & 1984)

Berkeley–Swansea Connection

• 1967: First FEM book **The Finite Element** Method in Structural and **Continuum Mechanics** Zienkiewicz

• 1977: 3rd edition – our first joint effort.

Swansea in 1969



Swansea – Shells work

REDUCED INTEGRATION TECHNIQUE IN GENERAL ANALYSIS OF PLATES AND SHELLS

O. C. ZIENKIEWICZ*

University of Wales, Swansea

R. L. TAYLOR[†] University of California, Berkeley, California

AND

J. M. TOO[‡] University of Wales, Swansea

Swansea: Reduced Integration









The first Swansea year

• First *FEAP*



Time Integration Developments

COMPUTER METHODS IN APPLIED MECHANICS AND ENGINEERING, 2, (1972) 69-97

EVALUATION OF NUMERICAL INTEGRATION METHODS IN ELASTODYNAMICS

G.L. GOUDREAU

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and

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People – MDG developers, analysts,		DYNA2D	NIKE2D	TOPAZ2D	Maze	<u>Orion</u>	MONT3D		

Error and stability analysis of discrete elastic problem

- Modal equation (elastic and undamped) $\ddot{d} + \omega^2 d = f$
- Newmark $d_{n+1} = d_n + \Delta t v_n + \left(\frac{1}{2} \beta\right) \Delta t^2 a_n + \beta \Delta t^2 a_{n+1}$ $v_{n+1} = v_n + (1 - \gamma) \Delta t a_n + \gamma \Delta t a_{n+1}$
- Let $\theta = \omega \Delta t$; $\delta = \gamma \frac{1}{2}$ and $\alpha^2 = \theta^2 / (1 + \beta \theta^2)$
- Eliminate velocity and acceleration and assume $d_k = \lambda^k$ gives $\lambda^2 - (2 - \alpha^2 - \delta \alpha^2)\lambda + (1 - \delta \alpha^2) = 0$

for homogeneous equation.

• Solution: $\lambda = (1 - \alpha^2 \delta)^{1/2} \exp(\pm ia)$ where

$$a = \tan^{-1} \left[\frac{\alpha \sqrt{1 - \frac{1}{4}\alpha^2 (1 + \delta)^2}}{1 - \frac{1}{2}\alpha^2 (1 + \delta)} \right]$$

Error and stability analysis (cont.)

- Results:
 - If $\gamma < \frac{1}{2}$ (or $\delta < 0$): Negative damping, unstable.
 - If $\gamma > \frac{1}{2}$ (or $\delta > 0$): Postive damping
 - For oscillatory response $1 + \frac{1}{4}\alpha^2(1+\delta)^2 \ge 0$
 - Gives stability limit on Δt : $\theta \leq \left[\frac{1}{4}(1+\delta)^2 \beta\right]^{-1/2}$
 - Unconditional stability requires: $\beta \ge \frac{1}{4}(1+\delta)^2$

EARTHQUAKE ENGINEERING & STRUCTURAL DYNAMICS, 5, (1976) 283-292

IMPROVED NUMERICAL DISSIPATION FOR TIME INTEGRATION ALGORITHMS IN STRUCTURAL DYNAMICS

H.M. HILBER, T.J.R. HUGHES and R.L. TAYLOR University of California, Berkeley





• HHT - Algorithm

$$Ma_{n+1} + Cv_{n+1} + (1 - \alpha)Kd_{n+1}$$

= $F_{n+1} + \alpha Kd_n$
$$d_{n+1} = d_n + \Delta tv_n + (\frac{1}{2} - \beta)\Delta t^2 a_n$$

+ $\beta \Delta t^2 a_{n+1}$
 $v_{n+1} = v_n + (1 - \gamma)\Delta ta_n + \gamma \Delta ta_{n+1}$

• Parameters:

$$\beta = \frac{1}{4} (1 - \alpha)^2$$
$$\gamma = \frac{1}{2} - \alpha$$
$$-\frac{1}{3} \le \alpha \le 0$$



Inelastic and Finite Deformation Problems
- Inelastic, contact & finite deformation developments. (with T.J.R. Hughes, W. Kanok-nukulchia, & A. Curnier)
- First UC Computational Mechanics Course (Spring 1975) (Taught by: K.S. Pister & T.J.R. Hughes)



• Established much of notation and methods we use today

The Juan Simo Years

- J.C. Simo (1952-1994)
- 1981-94: Interactions with many!



- 1981-94: Interactions with J.C. Simo
 - Developed method of solution for:
 - Integration of plasticity (plane strain & plane stress);
 - Enhanced strain elements;
 - Elasticity & viscoelasticity constitution in principal stretches;
 - Flexible-rigid body solutions;
 - Energy-momentum conserving integration methods;
 - Contributed to development of FEAP for finite deformation

Material Modeling: Elasto-Plastic

CONSISTENT TANGENT OPERATORS FOR RATE-INDEPENDENT ELASTOPLASTICITY* J.C. SIMO and R.L. TAYLOR Division of Structural Engineering and Structural Mechanics, Department of Civil Engineering, University of California, Berkeley, CA 94720, U.S.A.

Received 1 May 1984

- Developed algorithm for J_2 (Mises) plasticity
- Included isotropic and kinematic hardening
- Linearized return map algorithm
- Unaware Hibbitt had done perfect plasticity in Abaqus
- Later did plane stress case also.

Material Modeling: J₂ Elasto-Plastic Model

• Graphically, return map for J_2 form is



My Fifty Years with Finite Elements Material Modeling: Elasto-Plastic



Material Modeling: Finite Elasticity



Today

The FEM Today:

- By mid 1990's FEM for solids was fairly well established
 - Solve finite deformation solids, rods & shells
 - Treat near incompressibility; integrate inelastic constitutive models, etc.
 - Sparse solvers and eigen-problem methods available.
 - Research and commercial software available.
 - Personal computer/workstation costs reasonable.
- Thermal, Fluids, Electro-magnetics solvers also available.

Some Challenges for Today (and Tomorrow!)

- Multi-physics: Coupling of solids to multiple inputs.
 - Thermal; Electro-magnetics; Chemistry; Fluids, etc
- Multi-scale
 - Coupling between continuum-scale; meso-scale; etc.
- Automated analysis
 - From solid models to results with minimal user intervention
 - Challenges for element technology (tetrahedra)
 - Robust solvers (iterative & non-linear)

Summary:

- Described some of what I have witnessed in the last 50 years.
- Key contributions always occurred in collaboration with others!
- FEAP remains my "hobby" but still FEM is a lot of fun!
- I thank all (mentioned and unmentioned) I have had an opportunity to know during the last 50 years.
- Much accomplished, but much to do.
- I look forward to many more years of learning!







































Thank you for your attention!